Abstract

A car navigation apparatus includes a map data acquiring means 11 for acquiring map data, a current position detecting means 10 for detecting the current position of a car, a route searching means 12 for searching for a route to a destination based on the acquired map data, an intersection searching means 14 for searching for intersections in a vicinity of the current position from intersections which exist on the searched route and which exist between the current position and the destination, an intersection name outputting means 15 for outputting the names of the searched intersections, an intersection selecting means 17 for selecting an intersection from the intersection names outputted, an facility searching means 18 for searching for facilities which exist in a vicinity of the intersection selected through the map data, a facility name outputting means 19 for outputting the names of the searched facilities, a facility selecting means 20 for selecting a facility from the facility names outputted, and a facility information outputting means 21 for extracting facility information about the selected facility from the map data, and for outputting the facility information.